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FIG. 1

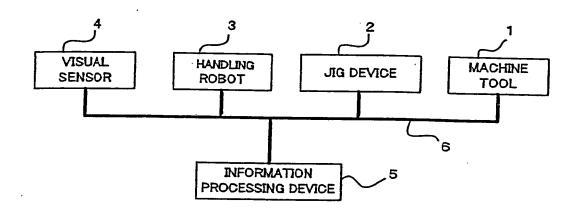


		FIG. 2		
KIND OF	VISUAL	HANDLING	1	MACHINE
WORKPIECE	SENSOR	ROBOT	JIG DEVICE	TOOL
K1		PNS0001	RIGHT	LX20
K2	W002	PNS0002	LEFT	LX21
кз	W002	PNS0003	RIGHT	LX22
K4	W002	PNS0003	RIGHT	LX23
K5	W003	PNS0004	UP	LX24
К6	W003	PNS0005	DOWN	LX25
K7	W012	PNS0006	RIGHT	LX26
КВ	.W003	PNS0007	LEFT	LX27



